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# Infinitely many states and stochastic symmetry in a Gaussian Potts-Hopfield model 

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Received 23 November 2001, in final form 1 February 2002
Published 8 March 2002
Online at stacks.iop.org/JPhysA/35/2581


#### Abstract

We study a Gaussian Potts-Hopfield model. Whereas for Ising spins and two disorder variables per site the chaotic pair scenario is realized, we find that for $q$-state Potts spins $q(q-1)$-tuples occur. Beyond the breaking of a continuous stochastic symmetry, we study the fluctuations and obtain the Newman-Stein metastate description for our model.


PACS numbers: $05.50 .+q, 75.50 . \mathrm{Lk}, 87.18 . \mathrm{Su}$

## 1. Introduction

In this paper we study the mean-field Potts model with Hopfield-Mattis disorder, in particular with Gaussianly distributed disorder. This model is a generalization of the model studied in [BvEN]. It provides yet another example of a disordered model with infinitely many lowtemperature pure states, such as is sometimes believed to be typical for spin glasses [MPV]. In our model, however, in contrast to that of $[B v E N]$, instead of chaotic pairs we find that the chaotic size dependence is realized by chaotic $q(q-1)$-tuples. For the notion of chaotic size dependence and the notion of chaotic pairs which were introduced by Newman and Stein, we refer the reader to [NS, NS2] and references therein. Compare also [BvEN] and [Nie]. For an extensive discussion of the Hopfield model, including some history and its relation with the theory of neural networks, see [B, p 133 and following] and [BG]. A somewhat different generalization of the Hopfield model to Potts spins was introduced by Kanter in $[\mathrm{K}]$ and was mathematically rigorously analysed in [G]. However, whereas the version we treat here (in which the form of the disorder is the Mattis-Hopfield one) displays the phenomenon of stochastic symmetry breaking, in which a finite-spin, 'finite-pattern' model can end up with chaotic size dependence, and a realization of chaotic $n$-tuples out of infinitely many 'pure states', we did not see how to obtain such results in a version of Kanter's form of the disorder distribution.

We are concerned in particular with the infinite-volume limit behaviour of the Gibbs and ground-state measures. The possible limit points are labelled as the minima of an appropriate
mean-field (free-) energy functional. These minima can be obtained as solutions of a suitable mean-field equation. These minima lie on the minimal-free-energy surface, which is an $m(q-1)$-sphere in the $\left(e^{1}, \ldots, e^{q}\right)^{\otimes m}$-space. This space for $q$-state Potts spins and $m$ patterns is formed by the $m$-fold product of the hyperplane spanned by the end points of the unit vectors $e_{q}$, which are the possible values of the spins. But only a limited area of the minimal-freeenergy surface is accessible. Only those values for which certain mean-field equations hold are allowed. These equations have the structure of fixed-point equations. We derive them in section 4. To obtain the Gibbs states we need to find the solutions of these equations on the minimal-free-energy surface.

The structure of the ground or Gibbs states for $q=2$ and $\xi^{k}$ Gaussian with $m=2$ has been known for a few years [BvEN]. Due to the Gaussian distribution, we have a nice symmetric structure: the extremal ground (and Gibbs) states form a circle. For a fixed configuration and a large finite volume, the possible order parameter values become close to two diametrical points (which ones depends on the volume of the system) on this circle. This paper treats the generalization of this structure to $q$-state Potts spins with $q>2$. To have a concrete example, we concentrate on the case $q=3$. It turns out that we again obtain a circle symmetry but also a discrete symmetry, which generalizes the one for Ising spins. One gets instead of a single pair a triple of pairs (living on three separate circles), where for each pair one has a similar structure to that for the single pair for $q=2$. For $q>3$ we get $(q(q-1)) / 2$ pairs and a similar higher-dimensional structure.

Our model displays quenched disorder. This means that we look at a fixed, particular realization of the patterns. It turns out that there is some kind of self-averaging. The thermodynamic behaviour of the Hamiltonian is the same for almost every realization. This is the case for the free energy and the associated fixed-point equations, as is familiar from many quenched disordered models. However, this is not precisely true for the order parameters. We will see that they show a form of chaotic size dependence, i.e. the behaviour strongly depends both on the chosen configuration and on the way in which one takes the infinite-volume limit $N \rightarrow \infty$ (that is, along which subsequence).

## 2. Notation and definitions

We start with some definitions. Consider the set $\Lambda_{N}=\{1, \ldots, N\} \in \mathbb{N}^{+}$. Let the singlespin space $\chi$ be a finite set and the $N$-spin configuration space be $\chi^{\otimes N}$. We denote a spin configuration by $\sigma$ and its value at site $i$ by $\sigma_{i}$. We will consider Potts spins, in the Wu representation $[\mathrm{Wu}]$. The set $\chi^{\otimes N}$ is then the $N$-fold tensor product of the set $\chi=\left\{e^{1}, \ldots, e^{q}\right\}$. The $e^{\sigma}$ are the projection of the spin vectors $e_{\sigma}$ on the hypertetrahedron in $\mathbb{R}^{q-1}$ spanned by the end points of $e_{\sigma}$. For $q=3$ we get for example for $e^{1}, e^{2}$ and $e^{3}$ the vectors

$$
\left\{\binom{1}{0},\binom{-\frac{1}{2}}{\frac{1}{2} \sqrt{3}},\binom{-\frac{1}{2}}{-\frac{1}{2} \sqrt{3}}\right\} .
$$

The Hamiltonian of our model is defined as follows:
$-\beta H_{N}=\frac{\beta}{N} \sum_{k=1}^{m} \sum_{i, j=1}^{N} \xi_{i}^{k} \xi_{j}^{k} \delta\left(\sigma_{i}, \sigma_{j}\right), \quad$ with $\quad \delta\left(\sigma_{i}, \sigma_{j}\right)=\frac{1}{q}\left[1+(q-1) e^{\sigma_{i}} \cdot e^{\sigma_{j}}\right]$,
where $\xi_{i}^{k}$ is the $i$ th component of the random $N$-component vector $\xi^{k}$. For the $\xi_{i}^{k}$ we choose i.i.d. $N(0,1)$ distributions. The vectors $\xi^{k}=\left(\xi_{1}^{k}, \ldots, \xi_{N}^{k}\right)$, by analogy with the standard Hopfield model, are called patterns. If we combine the above, we can rewrite the Hamiltonian $H_{N}$ as

$$
-\beta H_{N}=\beta \frac{q-1}{q} N \sum_{k=1}^{m}\left[\left(\frac{\sum \xi_{i}^{k} e^{\sigma_{i}}}{N}\right)^{2}+\frac{1}{q-1}\left(\frac{\sum \xi_{i}^{k}}{N}\right)^{2}\right] .
$$

So asymptotically

$$
\begin{align*}
-\beta H_{N} & =N \frac{K}{2} \sum_{k=1}^{m} q_{k N}^{2} \\
\text { with } K & =2 \beta\left(\frac{q-1}{q}\right) \text { and order parameters } q_{k N}=\frac{1}{N} \sum_{i=1}^{N} \xi_{i}^{k} e^{\sigma_{i}} . \tag{1}
\end{align*}
$$

The last term is an irrelevant constant; in fact it approaches zero, due to the strong law of large numbers. (The $\xi_{i}^{k}$ are i.i.d. $N(0,1)$ distributed, so $E \xi_{i}^{k}=0$.) Note that any i.i.d. distribution with zero mean, finite variance and symmetrically distributed around zero will give an analogous form of $H_{N}$, but we plan to consider only Gaussian distributions, for which we find that a continuous symmetry can be stochastically broken, just as in [BvEN]. From now on we drop the subscript $N$ to simplify the notation, when no confusion can arise.

Furthermore, we introduce two representations for the order parameters $\vec{q}$. If we assume $m=2$, then $\vec{q}=\left(\vec{q}_{1}, \vec{q}_{2}\right)$ and the definitions are as follows: if we consider the space $\mathbb{R}^{q-1}$ spanned by the vectors $e^{1}, \ldots, e^{q}$ the $\vec{x}$-plane, we define $\vec{q}=\left(x_{1}, \ldots, x_{2(q-1)}\right)$. It is often more convenient to look at the (higher-dimensional) $\left(e_{1}, \ldots, e_{q}\right)$-space. In that case we take $\vec{q}=\left(a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right)$ for $q=3$ and an equivalent equation for other values of $q$. For $m \neq 2$ the definitions are analogous.

## 3. Ground states

Now it is time to reveal the characteristics of the ground states for the Potts model. First we discuss the simple behaviour for one pattern. Then the more interesting part: $q>2$ and two patterns.

### 3.1. Ground states for one pattern

For one pattern $\xi$, the Hamiltonian is of the following form:

$$
-\beta H=N \frac{K}{2} \vec{q}_{1}^{2}=\frac{\beta}{N} \sum_{i, j=1}^{N} \xi_{i} \xi_{j} \delta\left(\sigma_{i}, \sigma_{j}\right)
$$

We easily see that the ground states are obtained by directing the spins with $\xi_{i}>0$ in one direction and the spins with $\xi_{i} \leqslant 0$ in a different direction. If we have as the distribution for the $\xi_{i} P\left(\xi_{i}= \pm 1\right)=\frac{1}{2}$, then the order parameter is of the form: $\vec{q}_{1}=\frac{1}{2}\left(e^{\sigma_{i}}-e^{\sigma_{j}}\right)$, with $1 \leqslant i, j \leqslant q$ and $i \neq j$; see also [vEHP]. So for $q=3$ we have only six ground states. They form a regular hexagon: $\left( \pm \frac{3}{4}, \mp \frac{\sqrt{3}}{4}\right), \pm\left(\frac{3}{4}, \frac{\sqrt{3}}{4}\right),\left(0, \pm \frac{\sqrt{3}}{2}\right)$. This regular hexagon with its interior is the convex set of possible order parameter values. It is easy to see that for $\xi_{i} N(0,1)$ distributed, we get the same ground states except for a scaling factor $\sqrt{2 / \pi}$ multiplying the values of the order parameter values.

### 3.2. Ground states for two patterns

The Hamiltonian for two patterns (Gaussian i.i.d.) is

$$
-\beta H_{N}=\frac{\beta}{N} \sum_{i, j=1}^{N}\left(\xi_{i} \xi_{j}+\eta_{i} \eta_{j}\right) \delta\left(\sigma_{i}, \sigma_{j}\right)=N \frac{K}{2}\left(\vec{q}_{1}^{2}+\vec{q}_{2}^{2}\right) .
$$

Similarly to in [BvEN], we make use of the fact that the distribution of two independent identically distributed Gaussians has a continuous rotation symmetry. This symmetry also shows up in the order parameters. Let
$\vec{q}_{1}(\theta)=\binom{x_{1}(\theta)}{x_{2}(\theta)}=\binom{\alpha \sin \theta}{\beta \sin \theta}, \quad \vec{q}_{2}(\theta)=\binom{x_{3}(\theta)}{x_{4}(\theta)}=\binom{\alpha \cos \theta}{\beta \cos \theta}$,
with $(\alpha, \beta)$ a ground state associated with the special case $\theta=0$ i.e. to the second pattern. We note that asymptotically for large $N$ we get the same ground-state energy per site for each value of $\theta$. Because the surface on which the Hamiltonian is constant is of the form $\vec{q}_{1}^{2}+\vec{q}_{2}^{2}=C^{2}$, these are the only ground states. For finite $N$, however, there are finitely many ( $q(q-1)$ ) ground states, corresponding to one particular value of $\theta$ (the exact symmetry of choosing a different pair of Potts directions gives the $q(q-1)$ ground states). This is an example of chaotic size dependence, based on the breaking of a stochastic symmetry, of the same nature as in [BvEN]. Because of weak compactness, different subsequences exist whose $q(q-1)$-tuples of ground states converge to $q(q-1)$-tuples, associated with particular $\theta$ values. These subsequences depend on the random pattern realization (see the appendix). For further background on chaotic size dependence and its role in the theory of metastates, we refer the reader to [NS].

For any finite $-m \geqslant 3$ patterns, one has the same discrete structure as before, but instead of a continuous circle symmetry, we have a continuous $m$-sphere symmetry (isomorphic to $O(m)$ ). The case of an infinite (that is, increasing with the system) $m$ is still open.

## 4. Positive temperatures

At positive temperatures, instead of minimizing an energy, one needs to minimize a free-energy expression.

By making use of arguments from large-deviation theory we obtain (see e.g. [HvEC])

$$
-\beta f(\beta)=\sup _{\vec{q}_{1}, \vec{q}_{2}}\left\{Q\left(\vec{q}_{1}, \vec{q}_{2}\right)-c^{\star}\left(\vec{q}_{1}, \vec{q}_{2}\right)\right\},
$$

where $f$ is the free energy per spin and $-\beta H=N \frac{K}{2}\left(\vec{q}_{1}^{2}+\vec{q}_{2}^{2}\right) \equiv N Q$. The function $c^{\star}$ is the Legendre transform of $c$, where $c$ is defined as follows:

$$
c(\vec{t})=\lim _{N \rightarrow \infty} \frac{1}{N} \ln \left\{\boldsymbol{E}_{\sigma} \exp \left(\vec{t}_{1} \cdot N \vec{q}_{1}+\vec{t}_{2} \cdot N \vec{q}_{2}\right)\right\}
$$

Here $\vec{t}_{1}$ and $\vec{t}_{2}$ are vectors in $\mathbb{R}^{q-1}$ and $\operatorname{tr}_{\sigma}$ is the normalized trace at a single site. To determine the supremum (maximum), we differentiate and put the derivative equal to 0 . This implies that for $\vec{q}_{1}$ and $\vec{q}_{2}$ the following holds:

$$
\begin{align*}
& K \vec{q}_{1}=\frac{\partial Q}{\partial \vec{q}_{1}}  \tag{3}\\
& K \vec{q}_{2}=\frac{\partial Q}{\partial \vec{q}_{2}} .
\end{align*}
$$

We make use of the fact that for a convex function $c, \nabla c^{\star}=(\nabla c)^{-1}$ (see also [BG, ch 3] and compare p 27 ). Now let us rewrite $c(\vec{t})$ :

$$
\begin{aligned}
c(\vec{t}) & =\lim _{N \rightarrow \infty} \frac{1}{N} \ln \left\{\boldsymbol{E}_{\sigma} \exp \left(\overrightarrow{t_{1}} \cdot N \vec{q}_{1}+\overrightarrow{t_{2}} \cdot N \vec{q}_{2}\right)\right\} \\
& =\cdots=\left\langle\ln ^{\operatorname{tr}}\left\{\exp \left(\xi \vec{t}_{1}+\eta \vec{t}_{2}\right) \cdot e^{\sigma}\right\}\right\rangle_{\xi, \eta} .
\end{aligned}
$$

Plugging this into (3) we get the mean-field equations for the order parameters which have the structure of a system of fixed-point equations $\overrightarrow{\boldsymbol{q}}=\boldsymbol{F}(\overrightarrow{\boldsymbol{q}})$ :

$$
\begin{align*}
& \vec{q}_{1}=\left\langle\frac{\operatorname{tr}_{\sigma}\left\{\xi e^{\sigma} \exp \left[K\left(\xi q_{1}+\eta q_{2}\right) \cdot e^{\sigma}\right]\right\}}{\operatorname{tr}_{\sigma}\left\{\exp \left[K\left(\xi q_{1}+\eta q_{2}\right) \cdot e^{\sigma}\right]\right\}}\right\rangle_{\xi, \eta}  \tag{4}\\
& \vec{q}_{2}=\left\langle\frac{\operatorname{tr}_{\sigma}\left\{\eta e^{\sigma}\left\{\exp \left[K\left(\xi q_{1}+\eta q_{2}\right) \cdot e^{\sigma}\right]\right\}\right.}{\operatorname{tr}_{\sigma}\left\{\exp \left[K\left(\xi q_{1}+\eta q_{2}\right) \cdot e^{\sigma}\right]\right\}}\right\rangle_{\xi, \eta} .
\end{align*}
$$

If we are in the allowed area, that is, the domain of definition of $\boldsymbol{F}$, it is equivalent to look in the $\left(\boldsymbol{e}_{1}, \ldots, \boldsymbol{e}_{q}\right)$-space. We may rewrite (4) in this area as follows:

$$
\begin{gathered}
\vec{q}_{1}=\left(\begin{array}{c}
a_{1} \\
\vdots \\
a_{q}
\end{array}\right)=\left(\begin{array}{c}
\left\langle\frac{\xi \exp K\left(\xi a_{1}+\eta b_{1}\right)}{\sum_{i=1}^{q} \exp K\left(\xi a_{i}+\eta b_{i}\right)}\right\rangle_{\xi, \eta} \\
\vdots \\
\left\langle\frac{\xi \exp K\left(\xi a_{q}+\eta b_{q}\right)}{\sum_{i=1}^{q} \exp K\left(\xi a_{i}+\eta b_{i}\right)}\right\rangle_{\xi, \eta}
\end{array}\right) \\
\vec{q}_{2}=\left(\begin{array}{c}
b_{1} \\
\vdots \\
b_{q}
\end{array}\right)=\left(\begin{array}{c}
\left\langle\frac{\eta \exp K\left(\xi a_{1}+\eta b_{1}\right)}{\sum_{i=1}^{q} \exp K\left(\xi\left(\xi a_{i}+\eta b_{i}\right)\right.}\right\rangle_{\xi, \eta} \\
\vdots \\
\left\langle\frac{\eta \exp K\left(\xi a_{q}+\eta b_{q}\right)}{\sum_{i=1}^{q} \exp K\left(\xi a_{i}+\eta b_{i}\right)}\right\rangle_{\xi, \eta}
\end{array}\right)
\end{gathered}
$$

with $\vec{q}_{1}=\sum_{i=1}^{q} a_{i} e_{i}$ and $\vec{q}_{2}=\sum_{i=1}^{q} b_{i} \boldsymbol{e}_{i}$.

### 4.1. Ising spins

If we look at the behaviour for $N \rightarrow \infty$, then due to the strong law of large numbers $(1 / N) \sum_{i=1}^{N} \xi_{i}=\boldsymbol{E} \xi=0$. Each coordinate $a_{j}$ of vector $\vec{q}_{1}=\left(a_{1}, a_{2}\right)$ is defined as $(1 / N) \sum_{i=1}^{N} \xi_{i} \delta\left(\sigma_{i}, \sigma_{j}\right)$. This means that $a_{j}$ is the contribution of the spins in the $j$ th direction to the $\operatorname{sum}(1 / N) \sum_{i=1}^{N} \xi_{i}$. Therefore: $a_{1}+a_{2}=(1 / N) \sum_{i=1}^{N} \xi_{i}=0$ a.e. This gives a necessary condition for the allowed area of Ising spins:

$$
\begin{equation*}
a_{1}=-a_{2} \wedge b_{1}=-b_{2} \tag{5}
\end{equation*}
$$

Furthermore, for all Gibbs states the value of the energy is constant; therefore:

$$
\begin{equation*}
a_{1}^{2}+a_{2}^{2}+b_{1}^{2}+b_{2}^{2}=\frac{r^{\star 2}}{2} \tag{6}
\end{equation*}
$$

When we substitute (5) in equation (6) and project the result to the $\left(x_{1}, x_{2}\right)$-plane by the projection $\Pi: e_{1} \rightarrow 1$, $e_{2} \rightarrow-1$, we obtain the following equation:

$$
x_{1}^{2}+x_{2}^{2}=r^{\star 2}
$$

Thus to get the radius of the circle of the Gibbs states $r^{\star}$, just take the point $\vec{q}_{1}=(a,-a), \vec{q}_{2}=$ $(0,0)$. This corresponds to the point $(2 a, 0)$ in the $\left(x_{1}, x_{2}\right)$-plane, by the projection $\Pi$. Of course $2 a=r^{\star}$.

With this we calculate the equation for the first coordinate of $\vec{q}_{1}$ in the $\left(e_{1}, e_{2}\right)$-plane by substituting the corresponding fixed-point equation:

$$
\begin{aligned}
a & =\frac{1}{2 \pi} \iint \xi \frac{\exp \beta \xi a}{\exp \beta \xi a+\exp (-\beta \xi a)} \exp \left(-\frac{\xi^{2}+\eta^{2}}{2}\right) \mathrm{d} \xi \mathrm{~d} \eta \\
& =\frac{1}{\sqrt{2 \pi}} \int \xi \frac{\exp \beta \xi a}{\exp \beta \xi a+\exp (-\beta \xi a)} \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi .
\end{aligned}
$$

We replaced $K$ by $\beta$, because for Ising spins $K=2 \beta(2-1) / 2=\beta$. We calculate the equation for the second coordinate of $\vec{q}_{1}$ in the same way. The vector $\vec{q}_{2}$ is simply $(0,0)$. Now project
$\vec{q}_{1}$ and $\vec{q}_{2}$ to the ( $x_{1}, x_{2}$ )-plane. That is done by subtracting the second coordinate of the $\vec{q}_{i}$ from the first one. We get the following equation for the radius $r^{\star}$ :

$$
\begin{equation*}
r^{\star}=\frac{1}{\sqrt{2 \pi}} \int \xi \tanh \left(\frac{\beta \xi r^{\star}}{2}\right) \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi \tag{7}
\end{equation*}
$$

For $\beta>\beta_{0}$ this equation has a nontrivial solution for $r^{\star}$. The equation is the same as in [BvEN] except the factor $1 / 2$ in the tanh. This is due to our using the Wu representation.

### 4.2. Potts spins

If we take $q=3$, then $K=\frac{4}{3} \beta$. The set of ground states now can be parametrized by three (in general $(q(q-1) / 2)$ ) circles, and similarly for the low-temperature Gibbs states. To obtain the radius $\hat{r}$ of such a circle parametrizing the ground or Gibbs states, we follow the same recipe as in the case of Ising spins. Here we take the point $\left(\vec{q}_{1}, \vec{q}_{2}\right)$ with $\vec{q}_{1}=(0, \hat{r} / \sqrt{3},-\hat{r} / \sqrt{3})$ and $\vec{q}_{2}=(0,0,0)$ (the representatives of both $\vec{q}_{i}$ in the ( $e_{1}, e_{2}, e_{3}$ )-plane). Now $\vec{q}_{1}$ projects to $(0, \hat{r})$ by the projection

$$
\binom{x_{1}}{x_{2}}=\left(\begin{array}{ccc}
1 & -\frac{1}{2} & -\frac{1}{2} \\
0 & \frac{1}{2} \sqrt{3} & -\frac{1}{2} \sqrt{3}
\end{array}\right)\left(\begin{array}{l}
a_{1} \\
a_{2} \\
a_{3}
\end{array}\right) .
$$

So if we substitute the corresponding fixed-point equations for $\vec{q}_{1}$ in the $\left(e_{1}, e_{2}, e_{3}\right)$-plane, we get for the order parameter values $\left(a_{1}, a_{2}, a_{3}\right) \equiv \vec{q}_{1}$ the following mean-field equations:

$$
\left(\begin{array}{l}
a_{1} \\
a_{2} \\
a_{3}
\end{array}\right)=\left(\begin{array}{c}
0 \\
\frac{1}{\sqrt{2 \pi}} \int \xi \frac{\exp (K \xi \hat{r} / \sqrt{3})}{\exp (K \xi \hat{r} / \sqrt{3})+\exp (-K \xi \hat{r} / \sqrt{3})+1} \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi \\
\frac{1}{\sqrt{2 \pi}} \int \xi \frac{\exp (-K \xi \hat{r} / \sqrt{3})}{\exp (K \xi \hat{r} / \sqrt{3})+\exp (-K \xi \hat{r} / \sqrt{3})+1} \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi
\end{array}\right) .
$$

Here $\left(a_{1}, a_{2}, a_{3}\right)=(0, \hat{r} / \sqrt{3},-\hat{r} / \sqrt{3})$. Thus by taking the difference between $a_{2}$ and $a_{3}$ and multiplying it by $\frac{1}{2} \sqrt{3}$, we finally get the following expression for the absolute value $\hat{r}$ :

$$
\begin{align*}
\hat{r} & =\frac{1}{2 \sqrt{\pi}} \sqrt{\frac{3}{2}} \int \xi \frac{\exp (K \xi \hat{r} / \sqrt{3})-\exp (-K \xi \hat{r} / \sqrt{3})}{\exp (K \xi \hat{r} / \sqrt{3})+\exp (-K \xi \hat{r} / \sqrt{3})+1} \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi \\
& =\frac{1}{\sqrt{\pi}} \sqrt{\frac{3}{2}} \int \frac{\xi \sinh (K \xi \hat{r} / \sqrt{3})}{2 \cosh (K \xi \hat{r} / \sqrt{3})+1} \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi \tag{8}
\end{align*}
$$

We can easily check that this expression indeed approaches the one for the radius for the circles through the ground states, by considering the behaviour of the integrand for $K \rightarrow \infty$. It behaves as follows:

$$
\int|\xi| \exp \left(-\frac{\xi^{2}}{2}\right) \mathrm{d} \xi
$$

Again, the case of $m$ an arbitrary finite number of patterns is a straightforward extension.

## Acknowledgments

This research was supported by the Samenwerkingsverband Mathematische Fysica. AvE thanks Christian Borgs for asking the question of how the results of [BvEN] generalize to Potts spins.

## Appendix A. Stochastic symmetry breaking for $q=3$

In this appendix we adapt the fluctuation analysis of [BvEN] to include Potts spins. We essentially follow the same line of argument, and find that the fluctuations, properly scaled, after dividing out the discrete symmetry, approach again a Gaussian process on the circle.

For notational simplicity we treat the case $q=3$ only. For $q>3$ a similar analysis applies. Define the function $\phi_{N, 2}$ as follows:

$$
\beta \phi_{N, 2}(\vec{z})=-Q(\vec{z})+\vec{z} \cdot \nabla Q(\vec{z})-c(\nabla Q(\vec{z}))
$$

where $c(\vec{t})$ equals
$c(\vec{t})=\frac{1}{N} \ln \left\{\boldsymbol{E}_{\sigma} \exp \vec{t}_{1} \cdot N \vec{q}_{1}+\vec{t}_{2} \cdot N \vec{q}_{2}\right\}=\frac{1}{N} \sum_{i=1}^{N} \ln \left\{\boldsymbol{E}_{\sigma_{i}} \exp \vec{t}_{1} \cdot \xi_{i} e^{\sigma_{i}}+\vec{t}_{2} \cdot \eta_{i} \boldsymbol{e}^{\sigma_{i}}\right\}$.
This $\phi_{N}$ is chosen such that for $N \rightarrow \infty$ the measure

$$
\tilde{\mathcal{L}}=\frac{\mathrm{e}^{-\beta N \phi_{N}}}{Z_{N, \beta}} \rightarrow \mathcal{L}
$$

where $\mathcal{L}$ is the induced distribution of the overlap parameters.
For $q=3$ the following holds:

$$
Q(\vec{z})=\frac{K}{2}\|\vec{z}\|_{2}^{2}=\frac{2}{3} \beta\|\vec{z}\|^{2}
$$

Thus,

$$
\begin{gathered}
\phi_{N, 2}(\vec{z})=\frac{2}{3}\|\vec{z}\|_{2}^{2}-\frac{1}{\beta N} \ln \left\{\boldsymbol{E}_{\sigma} \exp \frac{4}{3} \beta\left(\xi_{i} \vec{z}_{1} \cdot \boldsymbol{e}^{\sigma_{i}}+\eta_{i} \vec{z}_{2} \cdot e^{\sigma_{i}}\right)\right\} \equiv \frac{2}{3}\|\vec{z}\|_{2}^{2}-\frac{1}{\beta N} \boldsymbol{\Xi}_{N, 2} . \\
\begin{array}{c}
\Xi_{N, 2}=\sum_{i=1}^{N} \ln \left\{\frac{1}{3} \exp K\left(\xi_{i} z_{11}+\eta_{i} z_{21}\right)+\frac{2}{3} \exp -\frac{K}{2}\left(\xi_{i} z_{11}+\eta_{i} z_{21}\right) \cosh \frac{K \sqrt{3}}{2}\left(\xi_{i} z_{12}+\eta_{i} z_{22}\right)\right\} \\
=\sum_{i=1}^{N} \ln \left\{\frac{1}{3} \phi_{1}\left(z_{11}, z_{22}\right)_{\xi, \eta}+\frac{2}{3 \sqrt{\phi_{1}\left(z_{11}, z_{22}\right)_{\xi, \eta}}} \phi_{2}\left(z_{12}, z_{22}\right)_{\xi, \eta}\right\} .
\end{array}
\end{gathered}
$$

Because for finite $N$ the set of six Gibbs states has a discrete symmetry, as mentioned before, we choose out of these six states one state that we like, namely the one of the form $(0, \pm \alpha \sin \theta, 0, \pm \alpha \cos \theta)$. Note that the $\theta$ depends both on $N$ and on the realization of the random disorder variable. Then $z_{11}=z_{21}=0$ and $\phi_{1}=1$. Inserting this and defining $z_{12}=\tilde{z_{1}}$ and $z_{22}=\tilde{z_{2}}$, we get for $\phi$

$$
\phi\left(\tilde{z_{1}}, \tilde{z_{2}}\right)=\frac{2}{3}\left\|\left(\tilde{z_{1}}, \tilde{z_{2}}\right)\right\|_{2}^{2}-\frac{1}{\beta N} \sum_{i=1}^{N} \ln \left\{\frac{1}{3}+\frac{2}{3} \cosh \frac{2}{\sqrt{3}} \beta\left(\xi_{i} \tilde{z_{1}}+\eta_{i} \tilde{z_{2}}\right)\right\}
$$

Putting $\left(z_{1}, z_{2}\right)=\frac{2}{\sqrt{3}}\left(\tilde{z_{1}}, \tilde{z_{2}}\right)$ we obtain

$$
\phi\left(z_{1}, z_{2}\right)=\frac{1}{2}\left\|\left(z_{1}, z_{2}\right)\right\|_{2}^{2}-\frac{1}{\beta N} \sum_{i=1}^{N} \ln \left\{\frac{1}{2}+\cosh \beta\left(\xi_{i} z_{1}+\eta_{i} z_{2}\right)\right\}-\frac{1}{\beta N} \ln \frac{2}{3} .
$$

From now on the last term will be ignored. So it is enough to prove now that with the $\frac{1}{2}$ term we get the desired chaotic pair structure between the patterns due to the quenched disorder for this class of ground states, once we divide out the appropriate discrete Potts permutation symmetry. Thus the original model displays chaotic 6-tuples.

Therefore we only need to control the fluctuations of $\phi$. Define
$f_{N}^{\star}(\vec{z})-\boldsymbol{E} f_{N}^{\star}(\vec{z}) \equiv \frac{1}{\beta N} \sum_{i=1}^{N} \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\}-\frac{1}{\beta N} \sum_{i=1}^{N} \boldsymbol{E} \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\}$.
This is the fluctuation of the Ising case which we can estimate by [BvEN]. Denote the corresponding $\phi$-function by $\phi^{\star}$. We start with the following lemma:

## Lemma A.1.

$$
\begin{equation*}
\exp (-\beta N \phi) \leqslant \exp \left(-\beta N \phi^{\star}\right) \tag{10}
\end{equation*}
$$

Proof. Because

$$
\exp (-\beta N \phi)=\exp \left(-\beta N \boldsymbol{E} \phi^{\star}\right) \exp \left(-\beta N\left(\phi-\boldsymbol{E} \phi^{\star}\right)\right)
$$

we only have to estimate the quantity $\phi-\boldsymbol{E} \phi^{\star}$. Notice that also a lower bound is essential, because the quantity can become negative. First the estimate from above:
$\phi-\boldsymbol{E} \phi^{\star}=\frac{1}{\beta N} \sum_{i=1}^{N} \ln \left\{\frac{1}{2}+\cosh \beta \vec{z} \cdot(\xi, \eta)\right\}-\frac{1}{\beta N} \sum_{i=1}^{N} \boldsymbol{E} \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\}$.
Now use

$$
\begin{gathered}
\ln \left\{\frac{1}{2}+\cosh \beta \vec{z} \cdot(\xi, \eta)\right\}=\ln \left\{1+\frac{1}{2 \cosh \beta \vec{z} \cdot(\xi, \eta)}\right\}+\ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\} \\
\leqslant \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\}+\ln \frac{3}{2}
\end{gathered}
$$

to get

$$
\begin{align*}
\phi-\boldsymbol{E} \phi^{\star} \leqslant & \frac{1}{\beta N} \sum_{i=1}^{N} \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\}-\frac{1}{\beta N} \sum_{i=1}^{N} \boldsymbol{E} \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\}+\frac{1}{\beta} \ln \frac{3}{2} \\
& =f_{N}^{\star}(\vec{z})-\boldsymbol{E} f_{N}^{\star}(\vec{z})+\frac{1}{\beta} \ln \frac{3}{2} . \tag{11}
\end{align*}
$$

This is because $\cosh x \geqslant 1$ for all $x \in \mathbb{R}$.
The lower bound is easy because

$$
\frac{1}{\beta N} \sum_{i=1}^{N} \ln \left\{\frac{1}{2}+\cosh \beta \vec{z} \cdot(\xi, \eta)\right\} \geqslant \frac{1}{\beta N} \sum_{i=1}^{N} \ln \{\cosh \beta \vec{z} \cdot(\xi, \eta)\} .
$$

This is due to the fact that the function $\ln \alpha$ is monotonically increasing in $\alpha$. Then it follows that

$$
\begin{equation*}
\phi-\boldsymbol{E} \phi^{\star} \geqslant f_{N}^{\star}(\vec{z})-\boldsymbol{E} f_{N}^{\star}(\vec{z}) . \tag{12}
\end{equation*}
$$

Combine (11), (12) and use the fact that in the limit $\lim _{N \rightarrow \infty}$ the constant term $(1 / \beta) \ln \frac{3}{2}$ does not contribute to the expression $\exp \left\{-\beta N\left(\phi-\boldsymbol{E} \phi^{\star}\right)\right\}$ to conclude the proof of lemma A.1.

Henceforth it is convenient to transform $\phi^{\star}$ to polar coordinates. Define $z=(r \cos \theta$, $r \sin \theta$ ). Then (9) transforms to

$$
\begin{aligned}
\left|\bar{f}_{N}^{\star}(r, \theta)\right|= & \left|\frac{1}{\beta} \boldsymbol{E}_{\psi} \boldsymbol{E}_{\zeta} \ln \cosh \{\beta \zeta r \cos \psi\}-\frac{1}{\beta N} \sum_{i=1}^{N} \ln \cosh \left\{\beta r \zeta_{i} \cos \left(\theta-\psi_{i}\right)\right\}\right| \\
& =\left|\boldsymbol{E} f_{N}^{\star}(r, \theta)-f_{N}^{\star}(r, \theta)\right|
\end{aligned}
$$

Here $\zeta, \psi$ denote the polar decomposition of the two-dimensional vector $(\xi, \eta)$, i.e. $\zeta$ is distributed with density $x \exp -x^{2} / 2$ on $\mathbb{R}^{+}$and $\psi$ uniformly on the circle $[0,2 \pi)$. See [BvEN, p 188]. This we see easily because

$$
\begin{aligned}
\xi z_{1}+\eta z_{2}= & (\zeta \cos \psi)(r \cos \theta)+(\zeta \sin \psi)(r \sin \theta)=\zeta r(\cos \theta \cos \psi+\sin \theta \sin \psi) \\
& =\zeta r \cos (\theta-\psi) \quad \text { and } \quad \boldsymbol{E}_{\psi} \cos (\theta-\psi)=\boldsymbol{E}_{\psi} \cos \psi
\end{aligned}
$$

With $\phi^{\star}$ in this form, estimate (10) of lemma A. 1 is not very useful, since the fluctuations of $\phi$ reach their minimum for a different radius (in $\tilde{r}$ ) in general from the fluctuations of $\phi^{\star}$ (in $r^{\star}$ ). Thus we need to transform $\phi^{\star}$ such that the fluctuations of the transformed $\phi^{\star}$ reach their minimum at the same radius $\tilde{r}$ as those of $\phi$. This we achieve as follows. There is a uniform transformation $\Pi$ which translates all the points on the circle with radius $r^{\star}$ centred at the origin to the circle centred at the origin with radius $\tilde{r}$, the radius of $\phi$. If we apply $\Pi$ to $\phi^{\star}(r, \theta)$, then we get $\phi^{\star}\left(r+r^{\star}-\tilde{r}\right)$, the desired transformation of $\phi^{\star}(r, \theta)$. Now we can prove the next lemma:
Lemma A.2. For every $\epsilon>0$, the following holds:

$$
\begin{equation*}
\left|\bar{f}_{N}^{\star}(r, \theta)\right| \leqslant\left|\bar{f}_{N}^{\star}\left(r+r^{\star}-\tilde{r}, \theta\right)\right|+\epsilon \tag{13}
\end{equation*}
$$

The constant $r^{\star}$ is the radius of the circle parametrizing the set of mean-field solutions in the Ising case $(q=2)$. The constant $\tilde{r}$ is the radius $\hat{r}$ in the Potts case $q=3$ rescaled by the factor $2 / \sqrt{3}$; thus $\tilde{r}=(2 / \sqrt{3}) \hat{r}$.

Proof. We use the following estimate, which is lemma 2.5 from [BvEN]:

$$
\begin{equation*}
\left|\boldsymbol{E} f_{N}^{\star}(r, \theta)-f_{N}^{\star}(r, \theta)\right| \leqslant \frac{\epsilon}{2} \quad \text { a.e. on every bounded set. } \tag{14}
\end{equation*}
$$

Define

$$
\mathcal{O}=\left\{\vec{z} \in \mathbb{R}^{2}:\|\vec{z}\|>r^{\star}+\delta\right\}, \quad \mathcal{O}^{\prime}=\left\{\vec{z} \in \mathbb{R}^{2}:\|\vec{z}\|>\tilde{r}+\delta\right\} .
$$

Set $\mathcal{O} \subset \mathcal{O}^{\prime}$ because $\tilde{r} \leqslant r^{\star}$. Check this by using (7) and (8) and the scaling factor $2 / \sqrt{3}$ for $\tilde{r}$. Decompose $\mathcal{O}^{\prime}$ as $\mathcal{O} \cup \mathcal{O}^{\prime} \backslash \mathcal{O}$. Because $\mathcal{O}^{\prime} \backslash \mathcal{O}$ is a finite set, we can use estimate (14). With the estimate already obtained for $\mathcal{O}$ in [BvEN], equation (13) holds for all $(r, \theta) \in \mathcal{O}^{\prime}$. Because (14) is true for all finite sets, equation (13) holds for all ( $r, \theta$ ).

Note that in a neighbourhood of $\tilde{r}$ it is equivalent to look in a neighbourhood of $r^{\star}$. Now we are able to prove the following theorem:
Theorem A.1. Let $\mathcal{L}$ be the induced distribution of the overlap parameters and let $m=m(\theta)=$ $(\tilde{r} \cos \theta, \tilde{r} \sin \theta)$, where $\theta \in[0, \pi)$ is a uniformly distributed random variable. Then,

$$
\mathcal{L}_{N, \beta} \xrightarrow{\mathcal{D}} \frac{1}{2} \delta_{m(\theta)}+\frac{1}{2} \delta_{-m(\theta)} \equiv \mathcal{L}_{\infty, \beta}[m] .
$$

Furthermore, the (induced) AW-metastate is the image of the uniform distribution of $\theta$ under the measure-valued map $\theta \rightarrow \mathcal{L}_{\infty, \beta}[m(\theta)]$.
First we prove the following two lemmas:
Lemma A.3. For $\phi_{N}$ and $\xi_{i}, \eta_{i}$, with $i \in \mathbb{N}$ as defined above, there exist strictly positive constants $W, W^{\prime}, l, l^{\prime}$ such that ( $\tilde{r}$ is the largest solution of (8))

$$
\frac{\int_{|\|\vec{z}\|-\tilde{r}| \geqslant \delta_{N}} \mathrm{e}^{-\beta N \phi_{N}(\vec{z})} \mathrm{d} \vec{z}}{\int_{\|\vec{z}\|-\tilde{r} \mid<\delta_{N}} \mathrm{e}^{-\beta N \phi_{N}(\vec{z})} \mathrm{d} \vec{z}} \leqslant W \mathrm{e}^{-W N^{l}}
$$

on a set of $\boldsymbol{P}$-measure at least $1-W^{\prime} \mathrm{e}^{-K^{\prime} N^{\prime}{ }^{\prime}}$, where $\delta_{N}=N^{-\frac{1}{10}}$.

Lemma A.4. Assume the hypotheses of lemma A.3. Let $a_{N}=N^{-1 / 25}$. Then there exist strictly positive constants $K_{1}, K_{2}, C_{1}, C_{2}$ such that on a set of $\boldsymbol{P}$-measure at least $1-K_{1} \mathrm{e}^{-N^{1 / 25}}$ the following bound holds:

$$
\frac{\int_{A_{N}^{\prime}} \mathrm{e}^{-\beta N \phi_{N}(\vec{z})} \mathrm{d} \vec{z}}{\int_{A_{N}} \mathrm{e}^{-\beta N \phi_{N}(\vec{z})} \mathrm{d} \vec{z}} \leqslant C_{1} \mathrm{e}^{-N^{1 / 5}}
$$

where

$$
\begin{aligned}
& A_{N}=\left\{(r, \theta) \in \mathbb{R}_{0}^{+} \times[0,2 \pi)| | r-\tilde{r} \mid<\delta_{N}, g_{N}(\theta)-\min _{\theta} g_{N}(\theta)<a_{N}\right\} \\
& A_{N}^{\prime}=\left\{(r, \theta) \in \mathbb{R}_{0}^{+} \times[0,2 \pi)| | r-\tilde{r} \mid<\delta_{N}, g_{N}(\theta)-\min _{\theta} g_{N}(\theta) \geqslant a_{N}\right\}
\end{aligned}
$$

Here

$$
\begin{aligned}
g_{N}(\theta)=\frac{\sqrt{N}}{\beta} & \boldsymbol{E}_{\psi} \boldsymbol{E}_{\zeta} \ln \left\{\frac{1}{2}+\cosh \beta \zeta \tilde{r} \cos \psi\right\} \\
& -\frac{1}{\beta \sqrt{N}} \sum_{i=1}^{N} \ln \left\{\frac{1}{2}+\cosh \left\{\beta \tilde{r} \zeta_{i} \cos \left(\theta-\psi_{i}\right)\right\}\right\},
\end{aligned}
$$

which is the polar coordinate form of the function $g_{N}(\vec{z})$, which is defined as

$$
g_{N}(\vec{z})=\frac{1}{\sqrt{N}} \sum_{i=1}^{N}\left\{\ln \left\{\frac{1}{2}+\cosh \beta \vec{z} \cdot(\xi, \eta)\right\}-\boldsymbol{E} \ln \left\{\frac{1}{2}+\cosh \beta \vec{z} \cdot(\xi, \eta)\right\}\right\} .
$$

It is convenient to look at the following decomposition:
$\left(\phi_{N}-\boldsymbol{E} \phi_{N}\right)(\vec{z})=\beta \sqrt{N}\left(g_{N}\left(\vec{z}^{\prime}\right)+h_{N}(\vec{z})\right), \quad$ where $\quad h_{N}(\vec{z})=g_{N}(\vec{z})-g_{N}\left(\vec{z}^{\prime}\right)$.
The variable $\vec{z}^{\prime}$ is the projection of $\vec{z}$ onto $S^{1}(\tilde{r})$. Note that $\beta \sqrt{N} g_{N}=\phi_{N}-\boldsymbol{E} \phi_{N} \equiv \bar{f}_{N}$. Define $g_{N}^{\star}$ and $h_{N}^{\star}$ in the same way but as decompositions of $\bar{f}_{N}^{\star}$ instead of $\bar{f}_{N}$.
Proof of lemma A.3. Compare lemma 2.1 in [BvEN]. Define

$$
\begin{array}{ll}
\mathcal{O}=\left\{\vec{z} \in \mathbb{R}^{2}:\|\vec{z}\|>r^{\star}+\delta\right\}, & \mathcal{O}^{\prime}=\left\{\vec{z} \in \mathbb{R}^{2}:\|\vec{z}\|>\tilde{r}+\delta\right\}, \\
\mathcal{I}=\left\{\vec{z} \in \mathbb{R}^{2}:\|\vec{z}\| \leqslant r^{\star}-\delta\right\}, & \mathcal{I}^{\prime}=\left\{\vec{z} \in \mathbb{R}^{2}:\|\vec{z}\| \leqslant \tilde{r}-\delta\right\} .
\end{array}
$$

Now we first estimate the numerator which we can also write as

$$
\int_{\| \| \vec{z} \|-\tilde{r} \mid \geqslant \delta_{N}} \mathrm{e}^{-\beta N \phi_{N}(\vec{z})} \mathrm{d} \vec{z}=\int_{\mathcal{O}^{\prime} \cup \mathcal{I}^{\prime}} \mathrm{e}^{-\beta N E \phi_{N}(\vec{z})} \mathrm{e}^{-\beta N\left(\phi_{N}(\vec{z})-E \phi_{N}(\vec{z})\right)}
$$

With lemma A. 2 we have the following inequality:

$$
\begin{align*}
& \sup _{\vec{z} \in \mathcal{O}^{\prime}}\left|\bar{f}_{N}^{\star}(r, \theta)\right|-\epsilon \leqslant \sup _{\vec{z} \in \mathcal{O}^{\prime}}\left|\bar{f}_{N}^{\star}\left(r+r^{\star}-\tilde{r}, \theta\right)\right|=\sup _{\vec{z} \in \mathcal{O}}\left|\bar{f}_{N}^{\star}(r)\right| \\
& \boldsymbol{P}\left[\sup _{(r, \theta) \in \mathcal{O}^{\prime}}\left|\bar{f}_{N}^{\star}(r, \theta)\right|-\epsilon \geqslant \frac{C}{2}(r-\tilde{r})^{2}\right] \leqslant \boldsymbol{P}\left[\sup _{(r, \theta) \in \mathcal{O}}\left|\bar{f}_{N}^{\star}(r, \theta)\right| \geqslant \frac{C}{2}\left(r-r^{\star}\right)^{2}\right] . \tag{15}
\end{align*}
$$

Lemma 2.4 of $[\mathrm{BvEN}]$ tells us that this event is of measure zero. Now we can estimate the integral.

First we estimate $\boldsymbol{E} \phi_{N}^{\star}(\vec{z})$. Because $\boldsymbol{E} \phi_{N}^{\star}(\vec{z})$ is a bounded function, in each bounded interval one can always bound it from below by a function of the following kind:

$$
\boldsymbol{E} \phi_{N}^{\star}(\vec{z}) \geqslant C(\|\vec{z}\|-\tilde{r})^{2}+\boldsymbol{E} \phi_{N}^{\star}(\tilde{r}), \quad \text { with } C \text { a positive bounded constant. }
$$

Then

$$
\boldsymbol{E} \phi_{N}^{\star}\left(\vec{z}+r^{\star}-\tilde{r}\right) \geqslant C\left(\|\vec{z}\|-r^{\star}\right)^{2}+\boldsymbol{E} \phi_{N}\left(r^{\star}\right)
$$

when we apply $\Pi$ to this estimate. Now use estimate (15) with this constant $C$. Then the following holds:

$$
\begin{aligned}
& \int_{\mathcal{O}^{\prime}} \mathrm{e}^{-\beta N \boldsymbol{E} \phi_{N}(\vec{z})} \mathrm{e}^{-\beta N\left(\phi_{N}(\vec{z})-\boldsymbol{E} \phi_{N}(\vec{z})\right)} \mathrm{d} z \leqslant \int_{\mathcal{O}} \mathrm{e}^{-\beta N \boldsymbol{E} \phi_{N}^{\star}\left(\vec{z}+r^{\star}-\tilde{r}\right)} \mathrm{e}^{\beta N\left|\overline{f_{N}^{\star}}(\vec{z})\right|} \mathrm{e}^{\epsilon \beta N} \mathrm{~d} \vec{z} \\
& \leqslant \mathrm{e}^{-\beta N\left(\boldsymbol{E} \phi_{N}^{\star}\left(r^{\star}\right)-\epsilon\right)} \int_{\mathcal{O}} \mathrm{e}^{-\beta N C\left(r-r^{\star}\right)^{2}} \mathrm{e}^{\beta N(C / 2)\left(r-r^{\star}\right)^{2}} \mathrm{~d} r \\
&=\mathrm{e}^{\beta N\left(\boldsymbol{E} \phi_{N}^{\star}\left(r^{\star}\right)-\epsilon\right)} \int_{\mathcal{O}} \mathrm{e}^{-\beta N(C / 2)\left(r-r^{\star}\right)^{2}} \mathrm{~d} r \\
& \leqslant \cdots \leqslant 2 \pi \frac{2}{\beta N C} \exp \left(-\beta N\left(\boldsymbol{E} \phi_{N}^{\star}\left(r^{\star}\right)-\epsilon\right)\right) \exp -\beta N C_{2}\left(\frac{\delta^{2}}{4}\right)
\end{aligned}
$$

For further details see [BvEN]. The interior $\mathcal{I}$ gives a similar expression. Notice that the image of $\mathcal{I}$ under the transformation $\Pi: r \rightarrow r+r^{\star}-\tilde{r}$ is $\mathcal{I} \backslash B\left(0, r^{\star}-\tilde{r}\right)$. The ball $B\left(0, r^{\star}-\tilde{r}\right)$ is a finite set, so we can integrate over $\mathcal{I}$ instead of $\mathcal{I} \backslash B\left(0, r^{\star}-\tilde{r}\right)$ by (14). To estimate the denominator we just replace $r^{\star}$ by $\tilde{r}$ in the expressions of the proof of lemma 2.1 in [BvEN, p 192, 193]. Combining the estimates for the numerator and the denominator gives the desired result.

Proof of lemma A.4. From this moment we ignore the constants which enter on applying lemma A.1, because they cancel out when we divide the numerator by the denominator. For $\left|h_{N}\right|$ the following holds:

$$
\left|h_{N}\right| \leqslant\left|h_{N}^{\star}\right| \leqslant \epsilon
$$

by lemma 2.6 of [BvEN]. Consider the following integral:

$$
\int_{\theta: g_{N}(\theta)>a_{N}+\min _{\theta} g_{N}(\theta)} \mathrm{e}^{-\sqrt{N} g_{N}(\theta)} \leqslant 2 \pi \mathrm{e}^{-\sqrt{N}} \min _{\theta} g_{N}(\theta) \mathrm{e}^{\sqrt{N} a_{N}}
$$

Henceforth it is just a matter of plugging in to get the desired estimate on the denominator. We refer the reader to [BvEN] for the details. One gets a estimate for the denominator in the same way. By dividing the two estimates, lemma A. 4 is proven.

Proof of theorem A.1. In the preceding paragraphs we have seen that the measures $\tilde{\mathcal{L}}$ concentrate on a circle at the places where the random function $g_{N}(\theta)$ takes its minimum. Now it only remains to show that these sets degenerate to a single point, a.s. in the limit $N \rightarrow \infty$. If we have proven it for $\tilde{\mathcal{L}}$, then we have proven it also for $\mathcal{L}$, because $\lim _{N \rightarrow \infty} \tilde{\mathcal{L}}=\mathcal{L}$. With the help of $[\mathrm{BvEN}]$ this is very easy, because we can use proposition 3.4 with the function

$$
g(\cdot)=\ln \left\{\cosh \beta \cdot+\frac{1}{2}\right\}
$$

This works because $g$ is an aperiodic even function. And of course proposition 3.7 also holds for this $g$. These two propositions that we use tell us that the process $\eta_{N}=g_{N}(\theta)-\boldsymbol{E} g_{N}(\theta)$ converges to a strictly stationary Gaussian process, having a.s. continuously differentiable sample paths. And on any interval $[s, s+t], t<\pi$ the function $\eta_{N}$ has only one global minimum. Furthermore, if we define the sets

$$
L_{N}=\left\{\theta \in[0, \pi): \eta_{N}(\theta)-\min _{\theta^{\prime}} \eta_{N}\left(\theta^{\prime}\right) \leqslant \epsilon_{N}\right\},
$$

with $\epsilon_{N}$ some sequence converging to zero, $L_{N} \xrightarrow{\mathcal{D}} \theta^{\star}$. Then the remarks below Proof of theorem 3 in [BvEN] conclude the proof.

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